Opravenka

Opravenka ke skriptům: ŠKORPÍK, Jiří, 2022, *Teorie lopatkových strojů*, Akademické nakladatelství CERM, s.r.o., Brno, ISBN 978-80-214-6102-4.

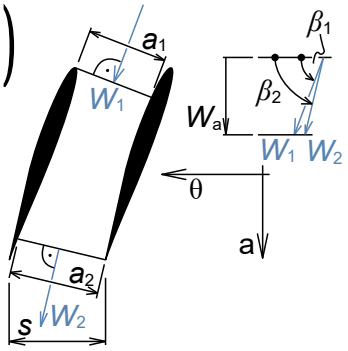
Rovnice 10, s. 4.9:

(a) $L_h = \frac{1}{\rho} L_p$ (b) $C_{L,is} = C_L - C_D \cdot \tan(\beta_m - 90°)$ (c) $C_D = \frac{2 L_h \cdot \sin\beta_m}{\sigma \cdot W_m^2}$

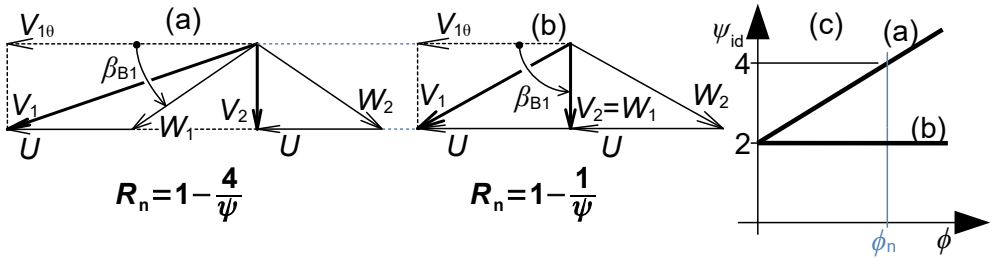
(d) $C_{L,is} = \frac{2}{\sigma}(\cot\beta_1 - \cot\beta_2)\sin\beta_m$

Rovnice 13, s. 4.12:

$$a_m \approx \frac{s}{2}\left(\frac{1}{\sin\beta_1} + \frac{1}{\sin\beta_2}\right)$$



Obrázek 14, s. 6.10:



$R_n = 1 - \frac{4}{\psi}$ $R_n = 1 - \frac{1}{\psi}$